

# Subexponential algorithm for discrete logarithm

Mathematical Cryptography,  
Lectures 22 - 23

- 1 Facts used in SEDL
  - Smooth numbers
  - Linear algebra over a field
- 2 Subexponential algorithm for discrete logarithm
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## Subexponential complexity

The subexponential algorithm for discrete logarithm (SEDL) builds on  $y$ -smooth integers and on linear algebra over the field  $\mathbb{Z}_p$ . Therefore, the algorithm SEDL works only for subgroups of  $\mathbb{Z}_p^*$ .

- Exponential complexity:  $O(n) = O(2^{\text{len}(n)})$
- Subexponential complexity:  $O(2^{f(\text{len}(n))})$ , where  $f(x) \in o(x)$ , i.e.  $\lim_{x \rightarrow \infty} \frac{f(x)}{x} = 0$ .  
The algorithm SEDL has complexity  $O(2^{c\sqrt{\text{len}(n)\text{len}(\text{len}(n))}})$ .  
For example, for  $n = 2^{256}$  it gives  $O(2^{\sqrt{256 \cdot 8}}) \doteq O(2^{47})$ .

## Smooth numbers

### Definition

Let  $y \geq 0$  be a real number. An integer  $m \geq 1$  is called to be  $y$ -smooth if all prime divisors of  $m$  are less than  $y$ .

Let  $0 \leq y \leq x$  be real numbers. Let us denote the number of all  $y$ -smooth numbers up to  $x$  as  $\Psi(y, x)$ .

### Examples

Numbers 4, 27, 24,  $9216 = 3^2 \cdot 2^{10}$  are 3-smooth.

$\Psi(2, 10) = 4$  since 1, 2, 4, 8 are all 2-smooth numbers up to 10.

$\Psi(3, 10) = 7$  since 1, 2, 3, 4, 6, 8, 9 are 3-smooth numbers up to 10.

Obviously  $\Psi(n, n) = n$  for any  $n \in \mathbb{N}$ .

## Smooth numbers

### Theorem 1

Let  $y = y(x)$  satisfy  $\lim_{x \rightarrow \infty} \frac{\ln(x)}{y} = 0$  and  $\lim_{x \rightarrow \infty} \frac{\ln(y)}{\ln(x)} = 0$ .  
Then

$$\Psi(y, x) \geq x e^{(-1+o(1)) \frac{\ln(x)}{\ln(y)} \ln(\ln(x))}$$

### Note

Recall that  $f \in o(g)$  in case  $\lim_{x \rightarrow \infty} \frac{f(x)}{g(x)} = 0$ .

The symbol  $o(1)$  represents a function  $f(x)$  for which  $\lim_{x \rightarrow \infty} f(x) = 0$ .

## Smooth numbers

### Theorem 2

Let  $y = y(x)$  satisfy  $y \in \Omega(\ln(x)^{1+\epsilon})$  for some  $\epsilon > 0$  and  $\lim_{x \rightarrow \infty} \frac{\ln(y)}{\ln(x)} = 0$ . Then

$$\Psi(y, x) = x e^{(-1+o(1)) \frac{\ln(x)}{\ln(y)} \ln(\frac{\ln(x)}{\ln(y)})}$$

### Note

Smooth numbers play an important role in the following subexponential algorithms. We will need estimates of how many they are for determining an expected running time of the algorithms.

## Linear algebra over a field

A linear algebra over the field  $\mathbb{Z}_p$  works just like over  $\mathbb{R}$ .

### Linear space over a field

A *linear space* over the field  $(T, +, \cdot)$  is the set  $L$  together with addition  $\oplus : L \times L \rightarrow L$  and numerical multiplication

$\square : T \times L \rightarrow L$  such that:

- $(L, \oplus)$  is an abelian group with an identity element  $\bar{0}$ ;
- For all  $\alpha, \beta \in T$  and all  $\bar{u}, \bar{v} \in L$ :
  - $\alpha \square (\bar{u} \oplus \bar{v}) = (\alpha \square \bar{u}) \oplus (\alpha \square \bar{v})$
  - $(\alpha + \beta) \square \bar{u} = (\alpha \square \bar{u}) \oplus (\beta \square \bar{u})$
  - $(\alpha \cdot \beta) \square \bar{u} = \alpha \square (\beta \square \bar{u})$
  - $1 \square \bar{u} = \bar{u}$

Elements of  $L$  are called vectors, elements of  $T$  scalars.

## Linear algebra over a field

### Linear space over a field

- A *subspace* of the linear space  $L$  is a nonempty subset  $P \subseteq L$  that is closed to addition and numerical multiplication.
- A *basis* of the linear subspace  $P$  is its linearly independent subset  $B = \{\bar{b}_1, \dots, \bar{b}_n\}$  which generates all the subspace  $P$ , so  $\bar{u} \in P$  just if  $\bar{u} = \sum_{i=1}^n a_i \bar{b}_i$ , where the  $n$ -tuple of coefficients  $(a_1 \dots a_n) \in T^{\times n}$  is uniquely determined.
- The  $n$ -tuple of coefficients is called the *coordinates* of the vector  $\bar{u}$  with respect to the ordered basis  $B$ .
- A number of elements of any basis of the subspace  $P$  is called the *dimension* of the subspace  $P$ , here  $\dim P = n$ .

## Linear algebra over a field

### Linear space over a field

- The vectors  $\bar{u}_1, \dots, \bar{u}_m$  are *linearly dependent* if there exist coefficients  $c_1, \dots, c_m \in T$  with at least one  $c_i \neq 0$  such that  $c_1\bar{u}_1 + \dots + c_m\bar{u}_m = \bar{o}$  (there exists a non-trivial linear combination of the vectors that equals to the zero vector).
- Let  $L$  be a linear space of dimension  $n$ , then any  $m > n$  vectors are linearly dependent.
- In particular, the set  $T^{\times n}$  of all  $n$ -tuples over the field  $T$  forms a linear space of the dimension  $n$ , so any  $n + 1$  vectors here form a linearly dependent set.

## Linear algebra over the field

### Systems of linear equations over a field

- The *Gaussian elimination algorithm* works over any field  $T$ , instead of dividing equations by their pivots, it uses multiplication by inverses of their pivots. (In the field  $T$ , every non-zero element has an inverse element.)
- Note: Over a ring (over  $\mathbb{Z}_n$ , where  $n$  is not a prime), Gaussian elimination does not work in general because the leading pivots need not to be invertible.
- The system of linear equations can have one solution, or no solution, or  $|T|^k$  different solutions, where  $k$  is the number of variables we are allowed to choose arbitrarily in  $T$ .

## Linear algebra over a field

### Systems of linear equations over a field

- All solutions of the homogeneous system  $A\bar{x}^T = \bar{o}^T$  form a subspace in  $T^{\times n}$  of dimension  $k$ , where  $k$  is the number of variables we are allowed to choose arbitrarily in  $T$ .
- Every solution of the system of equations  $A\bar{x}^T = \bar{b}^T$  is the sum of a partial solution of this system and some solution of the associated homogeneous system.

## Linear algebra over a field

### Matrix calculus over a field

- The matrix calculus over a field works just like over reals  $\mathbb{R}$  - we can define a determinant and a rank of a matrix, or calculate inverse matrices.
- Matrix calculus over a ring can be done with some specialities - e.g. the row rank need not be equal to the column rank (since Gaussian elimination does not work).
- A determinant of a matrix can be defined over a ring, invertible matrices are just those matrices that have an invertible determinant.

## SEDL algorithm

### Representation of an element

Let  $G$  be a cyclic group of order  $n$  with a generator  $a$ , and let  $b \in G$ . **Representation of the element**  $g \in G$  with respect to the generator  $a$  and the element  $b$  is any pair of numbers  $(s, t) \in \mathbb{Z}_n \times \mathbb{Z}_n$  such that  $g = a^s b^t$  in  $G$ .  
Moreover, if  $t \in \mathbb{Z}_n^*$ , then the representation is non-trivial.

### Proposition

- 1 For each  $t \in \mathbb{Z}_n$  there exists just one  $s \in \mathbb{Z}_n$  such that  $(s, t)$  is a representation of  $g$  with respect to the generator  $a$  and the element  $b$ .
- 2 If a non-trivial representation  $(s, t)$  of 1 with respect to  $a$  and  $b$  is known, then discrete logarithm can be computed:  
 $\text{dlog}_a(b) = -st^{-1}$  in  $\mathbb{Z}_n$ .

## SEDL algorithm

### Subexponential algorithm for discrete logarithm (SEDL)

Input:  $p, q, a, b, q$ ,  
where  $G = \langle a \rangle$  is a subgroup of order  $q$  in the group  $\mathbb{Z}_p^*$ ,  
 $p, q$  are primes,  
 $a$  is a generator of  $G, b \in G$ .  
Moreover, suppose that  $|\mathbb{Z}_p^*| = p - 1 = qm$ , where  $q \nmid m$ .  
(We'll discuss later how to proceed without this assumption.)  
Output:  $x = \text{dlog}_a(b)$ , or a report "failure".

The algorithm SEDL looks for a non-trivial representation of 1 with respect to  $a$  and  $b$ . If it finds any, it computes the discrete logarithm from it.

## Algorithm SEDL

### Proposition

Let  $|\mathbb{Z}_p^*| = qm$ , where  $p, q$  are primes and  $q \nmid m$ , and let  $G$  be a subgroup of order  $q$  and  $H$  be a subgroup of order  $m$  in  $\mathbb{Z}_p^*$ .  
Then  $\mathbb{Z}_p^* = G \dot{\times} H$  is an internal direct product of  $G$  and  $H$ , so

- $G \cap H = \{1\}$ ,
- $GH = \mathbb{Z}_p^*$ .

Or,  $G \times H \simeq \mathbb{Z}_p^*$  and each element  $z \in \mathbb{Z}_p^*$  can be written uniquely in the form  $z = gh$ , where  $g \in G$  and  $h \in H$ .

### Proposition

Let  $|\mathbb{Z}_p^*| = qm$ , where  $p$  is a prime, and let  $H$  be a subgroup of order  $m$  in the group  $\mathbb{Z}_p^*$ . Then for any element  $z \in \mathbb{Z}_p^*$  is  $z^q \in H$ .

## Algorithm SEDL

### First stage of the algorithm SEDL

We use  $y$ -smoothness, we will discuss an appropriate choice of the parameter  $y < p$  later on.

Let  $p_1, \dots, p_k$  be all primes up to  $y$ , so there are  $k$  many of them.

We find  $(k + 1)$   $y$ -smooth numbers from  $\mathbb{Z}_p^*$  by random, each of the form  $a^{s_i} b^{t_i} h_i$ , where  $a^{s_i} b^{t_i} = g_i \in G, h_i \in H$ .

We do this for every  $1 \leq i \leq k + 1$  as follows:

- choose randomly  $s_i, t_i \in \mathbb{Z}_q$  and  $\tilde{h}_i \in \mathbb{Z}_p^*$ , count  $h_i = \tilde{h}_i^q \in H$
- verify by trial division if  $z_i = a^{s_i} b^{t_i} h_i$  in  $\mathbb{Z}_p^*$  is  $y$ -smooth, i.e. whether  $z_i = p_1^{e_{i1}} \dots p_k^{e_{ik}}$  in  $\mathbb{Z}$  where  $0 < z_i < p$ , then  $a^{s_i} b^{t_i} h_i = p_1^{e_{i1}} \dots p_k^{e_{ik}}$  in  $\mathbb{Z}_p^*$
- if not, then repeat the random choice

## Algorithm SEDL

### First stage of the algorithm SEDL

Remark:

It would be sufficient to find randomly  $(k + 1)$   $y$ -smooth numbers from the subgroup  $G$ , each of the form  $a^{s_i} b^{t_i}$ , but we would not be able to estimate the expected time for searching because we don't know how many  $y$ -smooth numbers are in the subgroup  $G$ .

We can only estimate how many  $y$ -smooth numbers are up to  $p$ , so in  $\mathbb{Z}_p^*$ , and because of this we choose numbers of the form  $a^{s_i} b^{t_i} h_i = g_i h_i \in \mathbb{Z}_p^*$ .

## Algorithm SEDL

### Second stage of the algorithm SEDL

We use linear algebra over the field  $\mathbb{Z}_q$ , where  $q = |G|$ . We know that  $q$  is prime, therefore  $\mathbb{Z}_q$  is a field.

In the first stage, we have found  $(k + 1)$  equalities of shape:

$$a^{s_i} b^{t_i} h_i = p_1^{e_{i1}} \cdot \dots \cdot p_k^{e_{ik}} \text{ in } \mathbb{Z}_p^*$$

For each  $1 \leq i \leq k + 1$  we consider the  $k$ -tuple of exponents  $\bar{v}_i = (e_{i1}, \dots, e_{ik})$  as a vector over the field  $\mathbb{Z}_q$  for now.

The set  $\mathbb{Z}_q^{\times k}$  of all  $k$ -tuples over  $\mathbb{Z}_q$  forms a linear space of the dimension  $k$ . So our  $(k + 1)$  vectors must be linearly dependent, or there exists a non-trivial linear combination of them which equals to the zero vector.

## Algorithm SEDL

### Second stage of the algorithm SEDL

There exist coefficients  $c_1, \dots, c_{k+1} \in \mathbb{Z}_q$ , not all zero, such that

$$c_1 \bar{v}_1 + \dots + c_{k+1} \bar{v}_{k+1} = \bar{0} = (0, \dots, 0) \text{ in } \mathbb{Z}_q^{\times k}.$$

If we look at this combination over  $\mathbb{Z}$ , then all the components of the result vector are divisible by  $q$ .

$$c_1 \bar{v}_1 + \dots + c_{k+1} \bar{v}_{k+1} = (e_1, \dots, e_k) \text{ in } \mathbb{Z}^{\times k}, q \mid e_i \text{ for each } i.$$

We find the coefficients  $c_1, \dots, c_{k+1}$  using Gaussian elimination, which works over the field  $\mathbb{Z}_q$ .

(We will solve a homogeneous system of  $k$  equations for  $(k + 1)$  variables over  $\mathbb{Z}_q$ . We just need to find one non-trivial solution.)

## Algorithm SEDL

### Second stage of the algorithm SEDL

Consider again  $(k + 1)$  equalities  $a^{s_i} b^{t_i} h_i = p_1^{e_{i1}} \cdot \dots \cdot p_k^{e_{ik}}$  in  $\mathbb{Z}_p^*$  from the first stage. If we power each  $i$ -th equality to the corresponding  $c_i$  and multiply all the equalities by each other, we get the equality:

$$a^s b^t h = p_1^{e_1} \cdot \dots \cdot p_k^{e_k} \text{ in } \mathbb{Z}_p^*,$$

where  $s = \sum_{i=1}^{k+1} c_i s_i$ ,  $t = \sum_{i=1}^{k+1} c_i t_i$  in  $\mathbb{Z}_q$ ,  $h = \prod_{i=1}^{k+1} h_i^{c_i}$  in  $\mathbb{Z}_p^*$ .

Not all  $c_i$  are zero in  $\mathbb{Z}_q$ , so there could be  $s \neq 0$  and  $t \neq 0$ .

Moreover, we know that  $q \mid e_i$ , thus  $p_i^{e_i} \in H$  for each  $i$ .

## Algorithm SEDL

### Second stage of the algorithm SEDL

Finally, we have the equality

$$a^s b^t = h^{-1} p_1^{e_1} \cdot \dots \cdot p_k^{e_k} \text{ in } \mathbb{Z}_p^*,$$

where the element on the left is from the subgroup  $G$  and the element on the right is from the subgroup  $H$ .

But since  $G \cap H = \{1\}$  (see the assumption), this element must be equal to 1. We have found a representation of 1 with respect to the generator  $a$  and the element  $b$ ,

$$a^s b^t = 1 \text{ in } G \subseteq \mathbb{Z}_p^*.$$

If  $t \neq 0$ , we compute  $\text{dlog}_a(b) = -st^{-1}$  in  $\mathbb{Z}_q$ .

If  $t = 0$ , we report a failure.

## Algorithm SEDL

- for  $i \leftarrow 1$  to  $k + 1$  do
  - repeat
    - choose  $s_i, t_i \xleftarrow{\$} \mathbb{Z}_q, \tilde{h}_i \xleftarrow{\$} \mathbb{Z}_p^*$  at random
    - $h_i \leftarrow \tilde{h}_i^q, z_i \leftarrow a^{s_i} b^{t_i} h_i$  in  $\mathbb{Z}_p$
    - test if  $z_i$  is  $y$ -smooth (trial division)
  - until  $z_i = p_1^{e_{i1}} \cdot \dots \cdot p_k^{e_{ik}}$  for some  $e_{i1}, \dots, e_{ik} \in \mathbb{Z}$
  - $\tilde{v}_i \leftarrow (e_{i1}, \dots, e_{ik})$  in  $\mathbb{Z}^{\times k}$  enddo
- apply Gaussian elimination over  $\mathbb{Z}_q$  to find  $c_1, \dots, c_{k+1} \in \mathbb{Z}_q$ , not all zero, such that  $c_1 \tilde{v}_1 + \dots + c_{k+1} \tilde{v}_{k+1} = (0, \dots, 0)$  in  $\mathbb{Z}_q^{\times k}$
- $s \leftarrow \sum_{i=1}^{k+1} c_i s_i, t \leftarrow \sum_{i=1}^{k+1} c_i t_i$  in  $\mathbb{Z}_q$
- if  $t = 0$  in  $\mathbb{Z}_q$ 
  - then output "failure"
  - else  $x \leftarrow (-st^{-1})$  in  $\mathbb{Z}_q$  and output  $x$  endif

## Algorithm SEDL

### Example

$G = \langle 4 \rangle$  is a subgroup of order 11 in the group  $\mathbb{Z}_{23}^*$ ,  $|\mathbb{Z}_{23}^*| = 2 \cdot 11$ , so  $H = \{\pm 1\}$ . Count  $\text{dlog}_4(12)$  in  $\mathbb{Z}_{23}^*$  by SEDL and choose the parameter of smoothness  $y = 4$ .

(Note:  $12^{11} = 1$  in  $\mathbb{Z}_{23}^*$ , so  $12 \in G$  and  $\text{dlog}_4(12)$  is defined.)

- Stage 1 - we calculate in  $\mathbb{Z}_{23}^*$ , randomly we get the equations:
  - $R_1: 4^5 \cdot 12^7 \cdot 1 = 8 = 2^3$ , hence  $\tilde{v}_1 = (3, 0)$ .
  - $R_2: 4^4 \cdot 12^9 \cdot 1 = 12 = 2^2 \cdot 3^1$ , hence  $\tilde{v}_2 = (2, 1)$ .
  - $R_3: 4^3 \cdot 12^5 \cdot 1 = 2 = 2^1$ , hence  $\tilde{v}_3 = (1, 0)$ .

Note: The choice  $4^3 \cdot 12^5 \cdot (-1) = 21 = 3 \cdot 7$  was unsuccessful.

## Algorithm SEDL

### Example - continued

- Stage 2 - we count over  $\mathbb{Z}_{11}$ , by Gaussian elimination we find a non-trivial solution for  $c_1(3, 0) + c_2(2, 1) + c_3(1, 0) = (0, 0)$  which is  $c_1 = 1, c_2 = 0, c_3 = -3 = 8$ .
- Completing of calculations -  $R_1^1 \cdot R_2^0 \cdot R_3^8$  gives equality:  $4^{29} \cdot 12^{47} \cdot 1 = 2^{11} = 1$  in  $\mathbb{Z}_{23}^*$ , while  $4, 12 \in G$ , so we count modulo 11 in the exponent:  $4^7 \cdot 12^3 = 1$  in  $\mathbb{Z}_{23}^*$  is a non-trivial representation of 1.
- Hence  $3x + 7 = 0$  in  $\mathbb{Z}_{11}$ ,  $x = -7 \cdot 3^{-1} = 5$ . The discrete logarithm  $\text{dlog}_4(12) = 5$ .

## Algorithm SEDL

### Generalization of the algorithm SEDL

The algorithm SEDL can be modified to count discrete logarithm in a subgroup  $G$  of order  $q^e$  in  $\mathbb{Z}_p^*$ , where  $p, q$  are primes,  $|\mathbb{Z}_p^*| = q^e m$ ,  $q \nmid m$ . Let  $H$  be a subgroup of order  $m$  in  $\mathbb{Z}_p^*$ .

The algorithm SEDL still works because  $\mathbb{Z}_p^* = G \dot{\times} H$ .

The first stage proceeds in the same way, in the second stage we should solve a homogeneous system of equations over the ring  $\mathbb{Z}_{q^e}$ .

Gaussian elimination over a ring does not work in general, but in this case it can be modified so that it will find a non-trivial solution, which are coefficients  $c_1, \dots, c_{k+1} \in \mathbb{Z}_{q^e}$ , not all zero and even not all divisible by  $q$ . Then the counted  $t$  has a chance to be invertible in  $\mathbb{Z}_{q^e}$ , which happens if  $q \nmid t$ . So a non-trivial representation of 1 could be found, and the discrete logarithm can be computed.

## Algorithm SEDL

### Exercise

Suppose we are able to use the algorithm SEDL to compute the discrete logarithm in a subgroup  $G'$  of order  $q^e$  of the group  $\mathbb{Z}_p^*$ , where  $|\mathbb{Z}_p^*| = p - 1 = q^e m$ ,  $q \nmid m$ . Designe an algorithm that computes the discrete logarithm in the subgroup  $G$  of order  $q$  of  $\mathbb{Z}_p^*$ , where  $q \mid p - 1$  (without any further assumption on  $q$ ).

Input: the generator  $a$  of the group  $G$ ,  $b \in G$ ,  $p, q$  primes

Output:  $x = \text{dlog}_a(b)$  in  $G$

Hint: Note that  $G \subseteq G'$ . Find the generator  $c$  of the group  $G'$ , compute  $\text{dlog}_c(a)$ ,  $\text{dlog}_c(b)$  in  $G'$  and count  $x$  from them.

## Analysis of the algorithm SEDL

Let's go back to the basic version of the algorithm SEDL which computes the discrete logarithm of the element  $b$  in the subgroup  $G = \langle a \rangle$  of order  $q$  of the group  $\mathbb{Z}_p^*$ , where  $p, q$  are primes,  $|\mathbb{Z}_p^*| = p - 1 = qm$  and  $q \nmid m$ .

We want to analyze the output and the expected running time of the algorithm.

### Proposition

The probability that the algorithm SEDL reports a failure is  $\frac{1}{q}$ .

It can be shown that every  $t \in \mathbb{Z}_q$  can be found by the algorithm SEDL with the same probability. Then  $P[t = 0] = \frac{1}{q}$ .

## Analysis of the algorithm SEDL

### Expected time of the algorithm SEDL

- First stage: Let's denote by  $\sigma$  the probability that a random element from  $\mathbb{Z}_p^*$  is  $y$ -smooth. Then the expected number of loops for finding one  $y$ -smooth integer of the form  $a^{s_i} b^{t_i} h_i \in \mathbb{Z}_p^*$  equals to  $\frac{1}{\sigma}$ . We divide each integer by all  $k$  primes up to  $y$  ( $y < p$ ), which takes the time  $k \text{len}(p)^2$ . We need to find  $(k + 1)$  such  $y$ -smooth integers.  
 $E(\text{TIME1}) = O\left(\frac{k^2}{\sigma} \text{len}(p)^2\right)$
- Second stage: Gaussian elimination on a matrix of type  $(k, k + 1)$  requires roughly  $k^3$  operations in  $\mathbb{Z}_q$  and its time dominates in the second stage.  
 $\text{TIME2} = O(k^3 \text{len}(p)^2)$
- Expected time for SEDL:  $E(\text{TIME}) = O\left(\left(\frac{k^2}{\sigma} + k^3\right) \text{len}(p)^2\right)$

## Analysis of the algorithm SEDL

### Expected time of the algorithm SEDL

We shall estimate  $k$  and  $\sigma$  using  $y$ .

Assume that  $y = e^{\ln(p)^{\lambda+o(1)}}$ ,  $0 < \lambda < 1$ , so that we can use the Theorem 1 estimating the number of  $y$ -smooth integers up to  $p$ .

- $\sigma = \frac{\Psi(y, p-1)}{p-1} \geq \frac{\Psi(y, p)}{p} \geq e^{(-1+o(1))\frac{\ln(p)}{\ln(y)}} \ln(\ln(p))$
- By Chebyshev's theorem,  $k = \pi(y) = \Theta\left(\frac{y}{\ln(y)}\right)$ .  
So it can be deduced (for any  $y$ ) that  $k = e^{(1+o(1))\ln(y)}$ .
- $\ln(p)^2 = e^{o(1)\ln(y)}$  due to our assumption for  $y$ .

## Analysis of the algorithm SEDL

### Expected time of the algorithm SEDL

We plug in  $E(\text{TIME}) = O\left(\left(\frac{k^2}{\sigma} + k^3\right) \ln(p)^2\right)$  to get an estimate:

$$E(\text{TIME}) \leq e^{(1+o(1)) \max\left\{\frac{\ln(p)}{\ln(y)} \ln(\ln(p)) + 2\ln(y); 3\ln(y)\right\}}$$

Now we want to choose the parameter  $y$  so that the estimate of the expected time is minimal.

Let's denote  $\mu = \ln(y)$ ,  $A = \ln(p) \ln(\ln(p))$ .

We want to find a minimum of function  $f(\mu) = \max\left\{\frac{A}{\mu} + 2\mu; 3\mu\right\}$ , we use the basic calculus (zero first derivation).

## Analysis of the algorithm SEDL

### Expected time of the algorithm SEDL

For  $f_1(\mu) = \frac{A}{\mu} + 2\mu$  is  $f_1'(\mu) = -\frac{A}{\mu^2} + 2 = 0$  for  $\mu = \pm\sqrt{\frac{A}{2}}$ .

A local minimum is at  $\mu = \sqrt{\frac{A}{2}}$ , the value of the minimum is  $4\sqrt{\frac{A}{2}}$ .

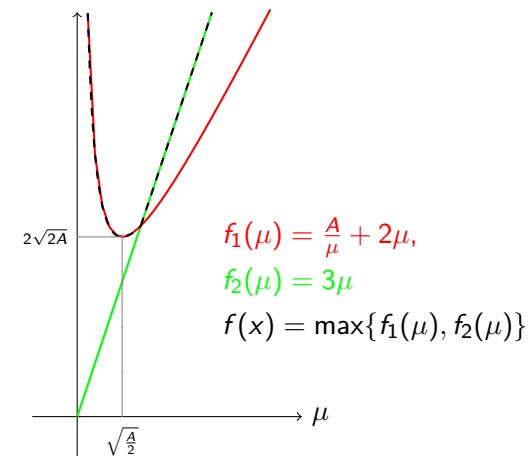
The function  $f_2(\mu) = 3\mu$  takes the value  $3\sqrt{\frac{A}{2}}$  in this point.

Thus  $\mu = \sqrt{\frac{A}{2}}$  is the minimum point for  $f(\mu) = \max\{f_1(\mu); f_2(\mu)\}$

and the value of the minimum is  $4\sqrt{\frac{A}{2}} = 2\sqrt{2A}$ .

## Analysis of the algorithm SEDL

### Expected time of the algorithm SEDL





### Expected time of the algorithm SEDL

We choose the parameter  $y = e^{\sqrt{\frac{A}{2}}} = e^{\frac{1}{\sqrt{2}}\sqrt{\ln(p)\ln(\ln(p))}}$   
(note that it satisfies the assumption of our calculation).

For this  $y$ , the expected time of algorithm SEDL will be

$$E(\text{TIME}) \leq e^{(2\sqrt{2}+o(1))\sqrt{\ln(p)\ln(\ln(p))}},$$

thus subexponential with constant  $2\sqrt{2} \doteq 2.828$  in the exponent.

### Note

The constant in the exponent can be reduced to 2.0 if we use a better estimate of number of  $y$ -smooth integers (Theorem 2).

### Literature

- Shoup: A Computational Introduction to Number Theory and Algebra. Chapter 15.
- Linear spaces over a field can be found in Chapter 13.  
<http://shoup.net/ntb/>