

Multidimensional Calculus. Useful formulas.

Line integrals.

Let C be a smooth space curve with parametric equations given by the vector function $\mathbf{r}(t) = \langle r_1(t), r_2(t), r_3(t) \rangle$, (or $\mathbf{r}(t) = \langle r_1(t), r_2(t) \rangle$ if $C \in \mathbb{R}^2$) $a \leq t \leq b$.

Given a scalar function f ($f(x, y, z)$ in \mathbb{R}^3 or $f(x, y)$ in \mathbb{R}^2) continuous on a region containing C , the line integral of f along C is

$$\int_C f ds = \int_a^b f(\mathbf{r}(t)) \|\mathbf{r}'(t)\| dt.$$

Given a continuous vector function \mathbf{F} defined on C

($\mathbf{F}(x, y, z) = \langle M(x, y, z), N(x, y, z), P(x, y, z) \rangle$, or $\mathbf{F}(x, y) = \langle M(x, y), N(x, y) \rangle$)

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt.$$

Fundamental Theorem for line integrals. $\int_C \nabla f \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$.

Green's Theorem. Let C be a positively oriented, piecewise smooth, simple **closed** curve in the plane, D the region bounded by C . Given $\mathbf{F}(x, y) = \langle M(x, y), N(x, y) \rangle$ s.t. M, N have continuous partial derivatives on an open region containing D

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C M dx + N dy = \iint_D \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA$$

Surface integrals.

Let S be an oriented surface with parametric equations given by $\mathbf{r}(u, v) = \langle r_1(u, v), r_2(u, v), r_3(u, v) \rangle$, $(u, v) \in D$.

$$\iint_S f dS = \iint_D f(\mathbf{r}(u, v)) \|\mathbf{r}_u \times \mathbf{r}_v\| dA$$

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D \mathbf{F} \cdot (\mathbf{r}_u \times \mathbf{r}_v) dA$$

Definition. The Curl of a vector field is a vector field:

$$\text{curl } \mathbf{F} = \nabla \times \mathbf{F} = \left\langle \frac{\partial P}{\partial y} - \frac{\partial N}{\partial z}, \frac{\partial M}{\partial z} - \frac{\partial P}{\partial x}, \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right\rangle.$$

Definition. The Divergence of a vector field is a scalar function

$$\text{div } \mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}.$$

Stokes' Theorem. Let S be an oriented piecewise-smooth surface bounded by a simple, closed, piecewise-smooth curve C with positive orientation. \mathbf{F} a vector field whose components have continuous partial derivative on an open region containing S :

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S}.$$

Gauss (Divergence) Theorem. Let E be a solid region whose boundary surface S has positive orientation (outward). \mathbf{F} a vector field whose components have continuous partial derivative on an open region containing E :

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iiint_E \text{div } \mathbf{F} dV$$